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#### **Contextual ISR**





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#### Introduction

**Special Operations Solutions, LLC** (SOS) specializes in technical and engineering support for airborne, ground, maritime and virtualized systems.

SOS provides engineering solutions and consulting for all life cycle phases. Our team of engineers have designed and developed power distribution units, system architectures, data links, video distribution solutions and complex aircraft networks.

Founded in 2008 and headquartered in Tysons, Virginia, USA.

Offices in Washington DC metro, Harrisonburg, VA, and Bangalore India.

Subsidiary in India called GeoOpsis which focuses on GIS software development.

SOS's customers are U.S. Army, U.S. Air Force, Solar Ship, Bertolini (Airship do Brasil)



#### ISR

**Intelligence, Surveillance, and Reconnaissance (ISR)** is the ability to capture data from various sources and analyze it to create intelligence.

Aerial ISR is another name for aerial remote sensing. The sources are sensors (i.e. radars, EO/IR full motion video, multispectral, hyperspectral, signals and communications equipment, etc).

Full motion video (FMV) is the center of most data collections. FMV consists of any system that has at least one camera system. Most defense FMV sensors contain at least two sensors (visible and thermal). ISR assets including commercial off-the-shelf drones provide a camera on it.

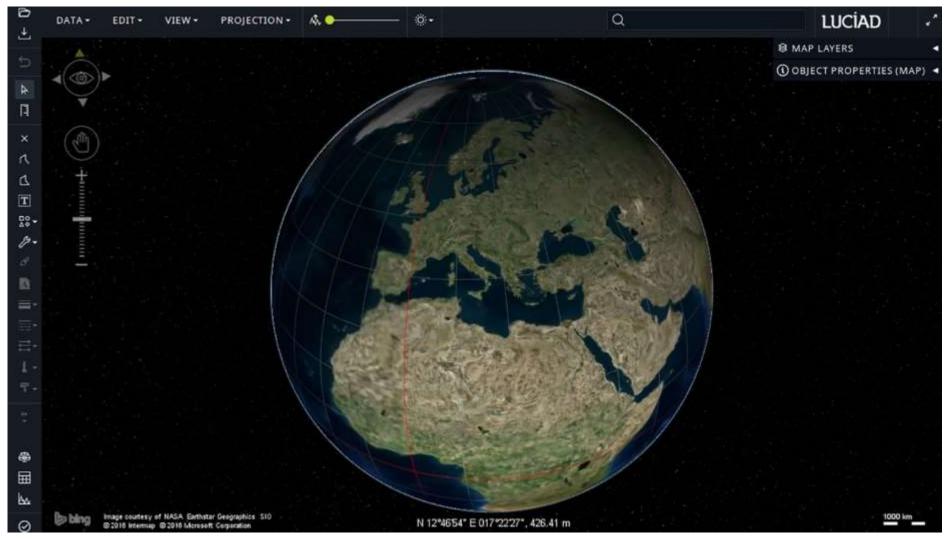
At the GEOINT event in May, NGA Director Robert Cardillo said,

"And whether our new persistent view of the world comes from space, air, sea, or ground – in five years, there may be a million times more than the amount of geospatial data that we have today. Yes, a million times more."



# Step 1: Get A Map

SOS partnered with Luciad to create a 2D and 3D map using standardized data from various sources.



#### Step 2: Get A Database

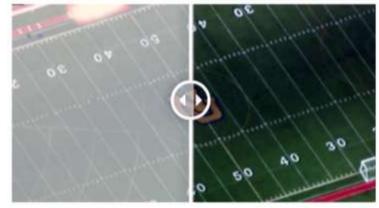
SOS created a database schema which can ingest most standardized datasets from various sensors and reports. This can occur for real-time data (i.e. active FMV sensor) or archived data (recorded FMV).



## Step 3: Add Tools



**Color Balancing** 



#### Haze Reduction



**Histogram Equalization** 



Multi-Layers



Measurements, Annotations, etc



Change Detection

## Step 4: Add Context

SOS allowed users to query the database based on keywords, spatial, and temporal constraints.

| Event Sea  | rch          |             |  |                               | ×       |
|--|--------------|-------------|--|-------------------------------|---------|
| <ul> <li>Spatial Constraints</li> <li>Map Extents</li> </ul> |              |             | <ul> <li>Temporal Constraints</li> <li>Simple</li> </ul> |                               |         |
| NE:  | 34.619217    | -118.039978 |  | 1.0 🍦 days.                   |         |
| SW:  | 34.551300    | -118.249310 | O Precise<br>Start:                                      | Tue, 15 Aug 2017 07:32:30 GMT |         |
| O Target Radius  |              |             |  |                               |         |
| LatLon:  | 90.000000    | 000.000000  | Finish:  | Tue, 15 Aug 2017 07:32:30 GMT |         |
| MGRS:  | ZAH000000000 |             | Target Constraints                                       |                               |         |
| Dist (m):  | 100.000      |             | ID:  |                               |         |
| Location Constraints   |              |             |  |                               |         |
| O Province   |              |             | District   |                               |         |
|  |              |             |  |                               |         |
| Keyword Constraints  |              |             |  |                               |         |
|  |              |             |  |                               |         |
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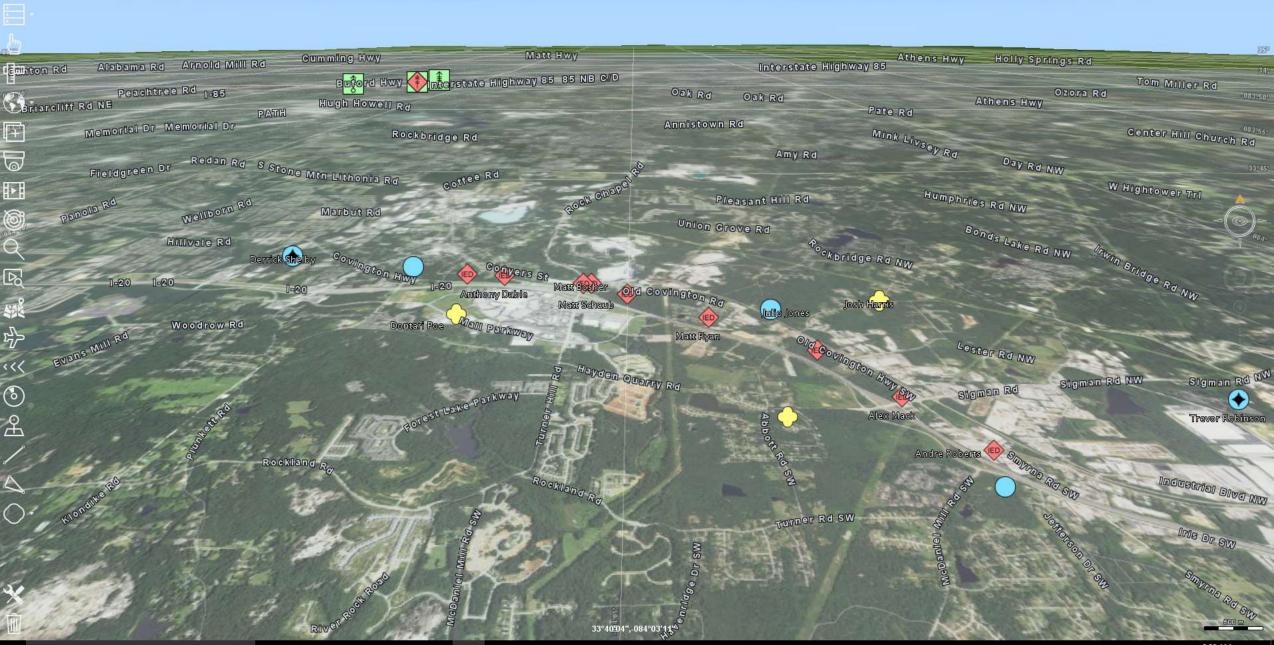
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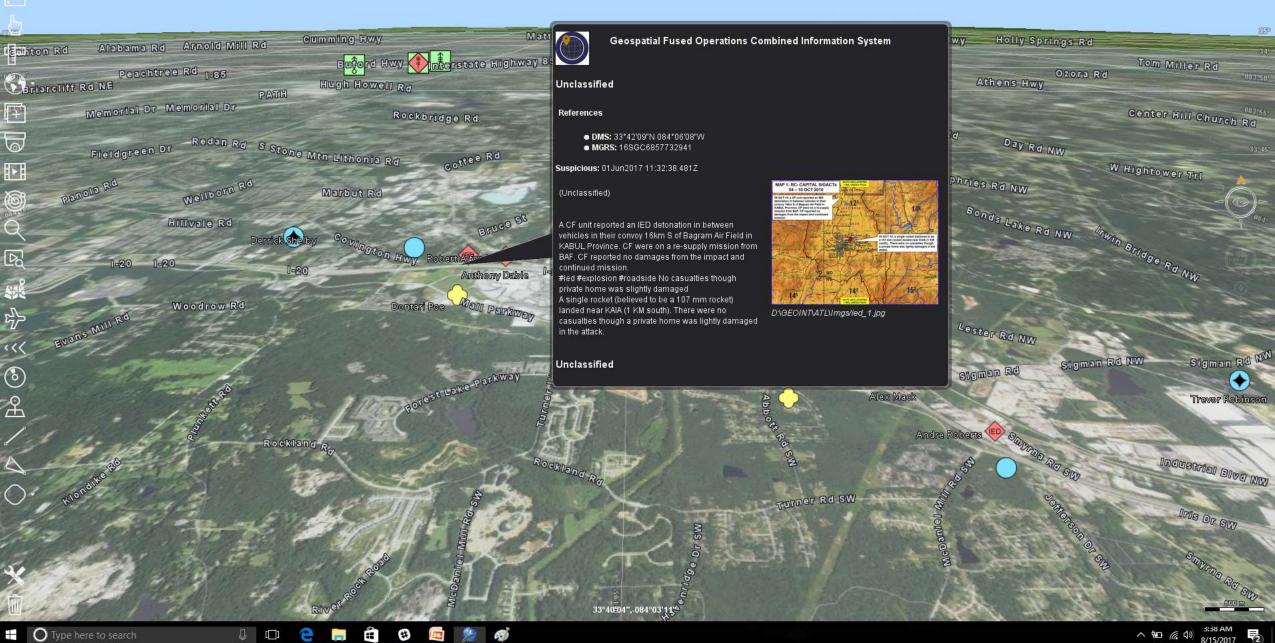


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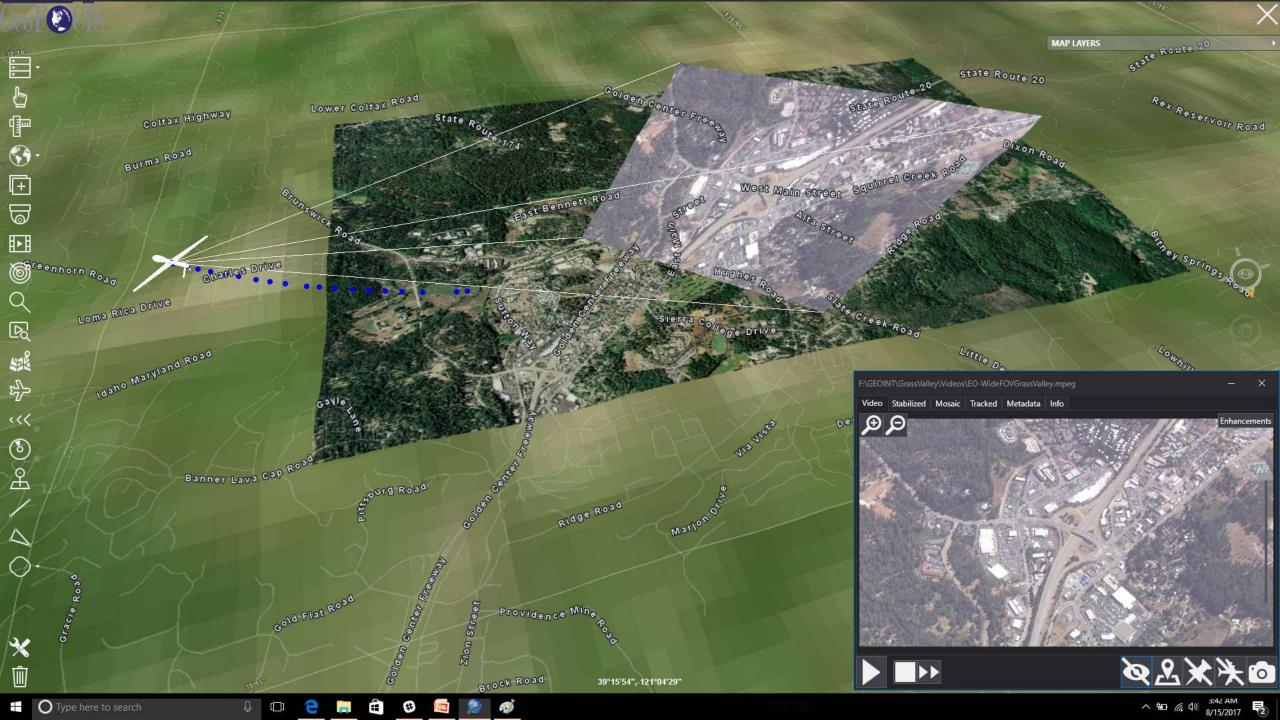


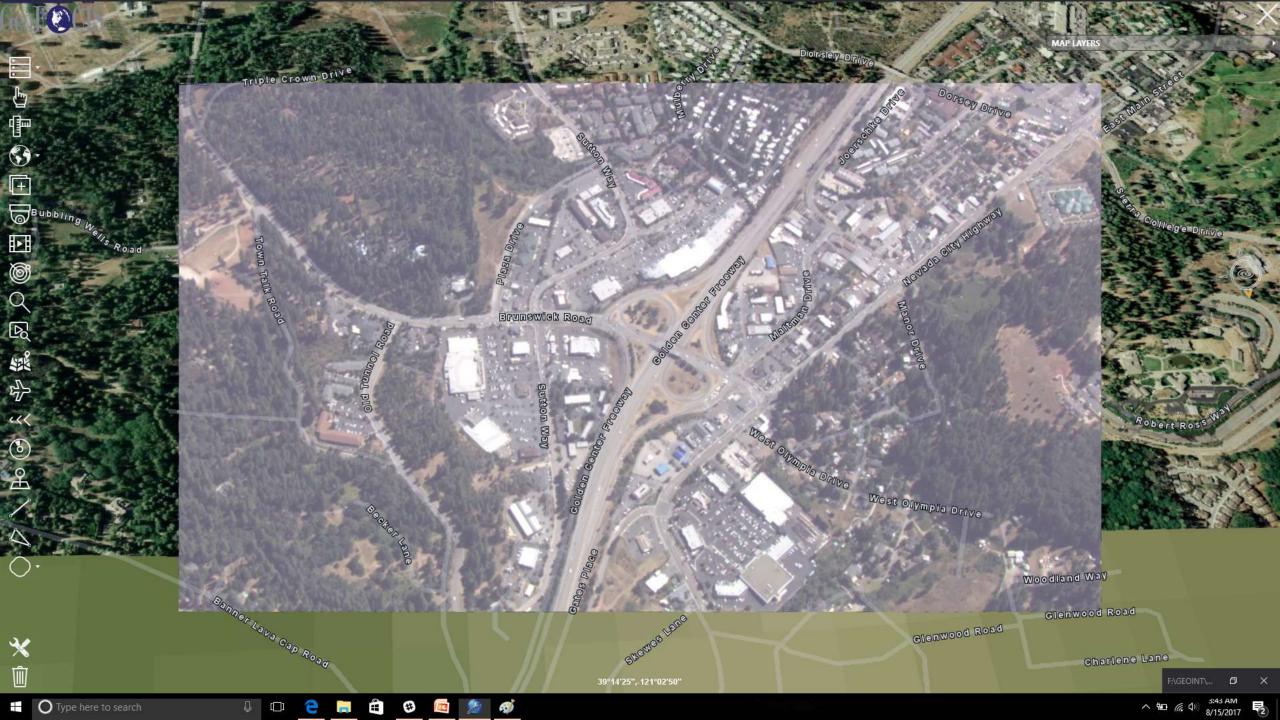
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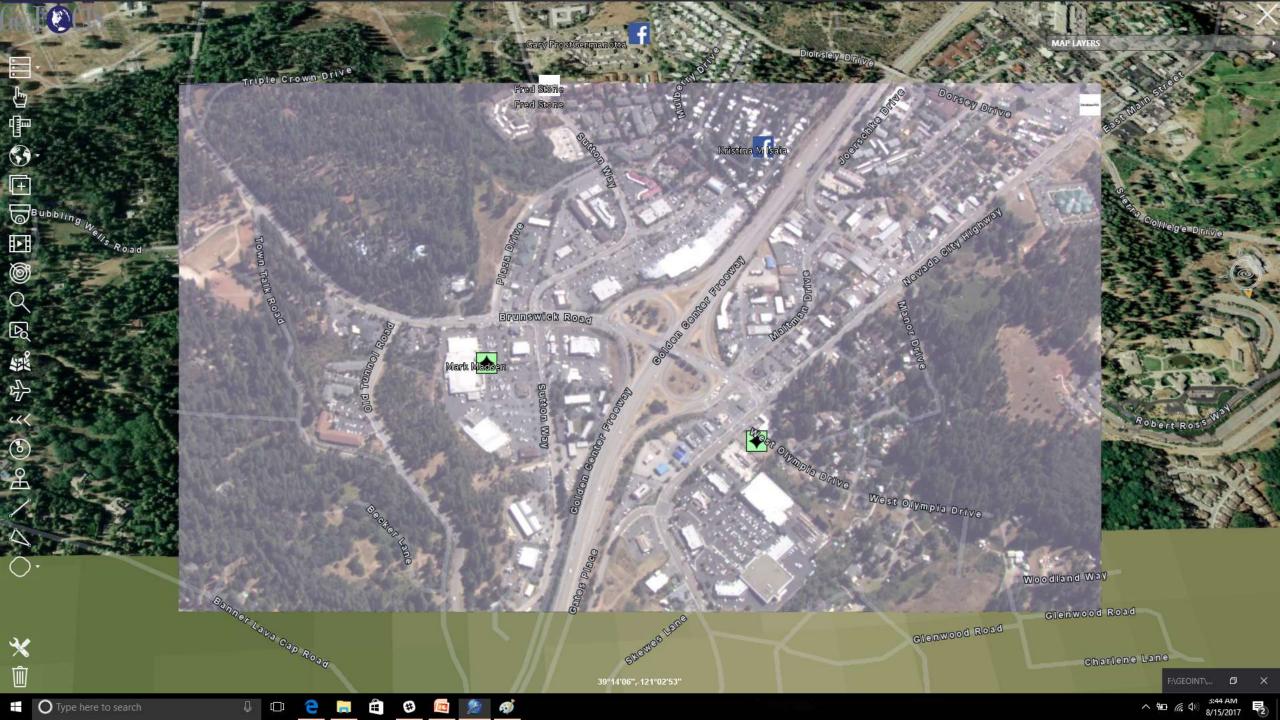
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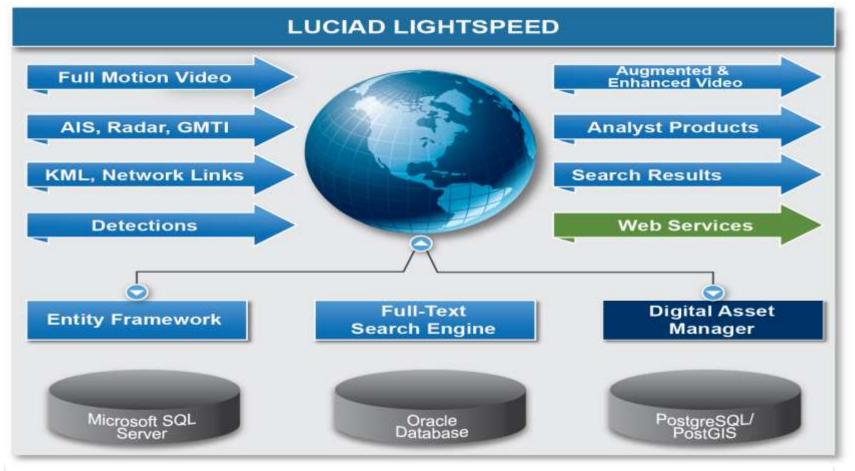






### **GeoFOCIS** Architecture

**GEOFOCIS** embeds the LuciadLightspeed engine and uses it to display a 3D globe with highresolution reference imagery, road networks, AIS, radar and real-time video-on-terrain. It further augments the display with feature data, such as, previous sensor detections, stored in its geospatial database.



SOS uses LuciadFusion to build high resolution Luciad globes using imagery from commercial sources such as Digital Globe. The globes are compacted into one file and sent to a deployed stand alone environment to use in a portable fashion..

