



Evaluating the Effect of Global Positioning System (GPS) Antenna Orientation on GPS Performance



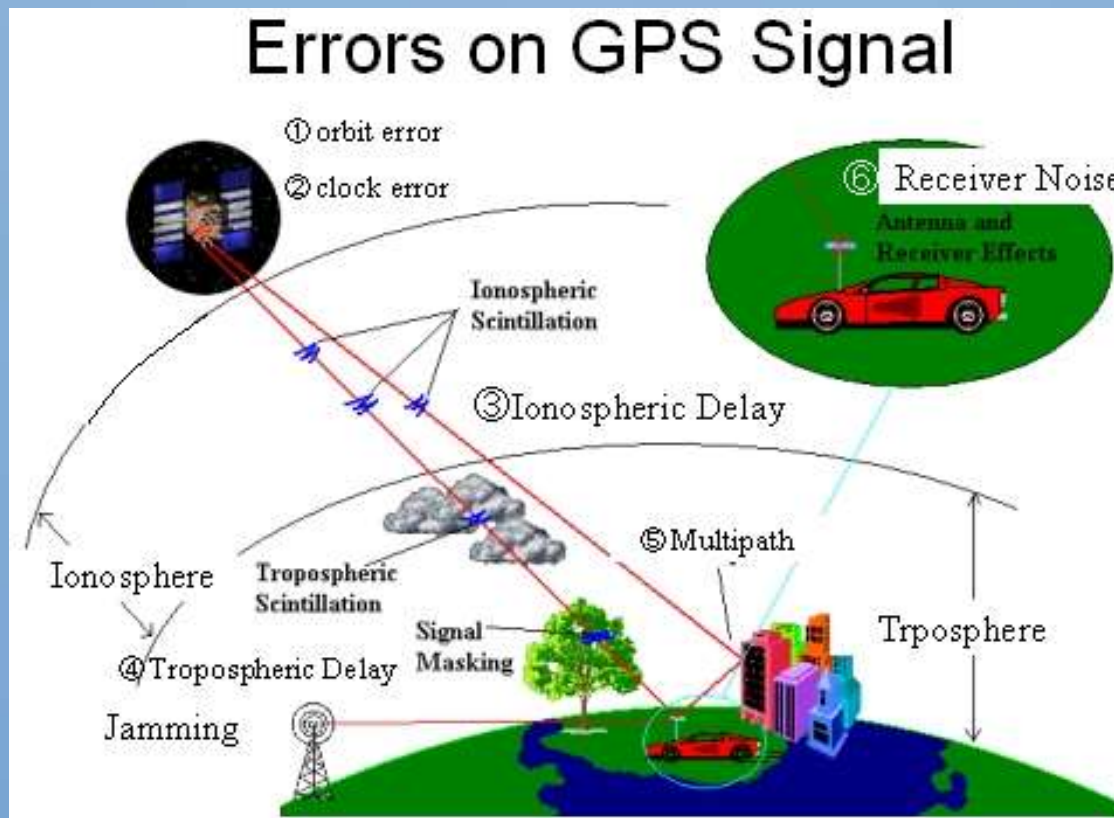
Introduction

Increasing
use for PNT
applications:

- ◆ Positioning
- ◆ Navigation
- ◆ Timing



GNSS Vulnerabilities



Source: IranMap.com

GNSS Receiver Evaluation

- ◆ Many designers are working on improving characteristics of GNSS receivers, such as:
 - ◆ Lower power consumption
 - ◆ Tracking of weak satellite signals
 - ◆ Acquisition time
 - ◆ Positioning and timing accuracy
 - ◆ Radio frequency interference (RFI) interoperability
- ◆ Many developers and users still struggle to identify suitable standard tests to objectively verify and evaluate the functionality and performance of GNSS receivers.



GNSS Receiver Evaluation

Field Evaluation



- ◆ Employs live GNSS signals.
- ◆ Should be conducted in open area with clear view of the sky.
- ◆ Tests scenarios are uncontrollable by users and not repeatable.

GNSS Simulation



- ◆ Employs simulated GNSS signals.
- ◆ Should be conducted in a RF enclosure (e.g. anechoic chamber).
- ◆ Test scenarios are user controllable and repeatable.



Research Theme

Title: Simulation and Modelling of Global Navigation Satellite System (GNSS) Vulnerabilities

Research Objectives:

- ◆ GNSS simulation will be used to model the effect of the following vulnerabilities on GNSS receiver performances:
 - ◆ Radio frequency interference (RFI)
 - ◆ Spoofing
 - ◆ Ionospheric and tropospheric delays
 - ◆ LOS blockage and multipath errors



R&D Projects Conducted

Num.	Project Title	Status	Duration
1	Evaluation of the Effect of Radio Frequency Interference (RFI) on Global Positioning System (GPS) Signals	Internal	November 2009 – June 2010
2	Evaluation of the Effect of Radio Frequency Interference (RFI) on Global Positioning System (GPS) Signals via GPS Simulation	RMK10	January 2011 – May 2012
3	Evaluation of the Effect of Multipath on Global Positioning System (GPS) Signals via GPS Simulation	Internal	January 2013 – January 2014
4	Evaluation of the Effect of Global Positioning System (GPS) Satellite Clock Error via GPS Simulation	Internal	April – September 2014
5	Evaluation of Trade-Off Between Global Positioning System (GPS) Accuracy and Power Saving from Reduction of Number of GPS Receiver Channels	Internal	November 2014 – March 2015
6	Evaluation of the Accuracy of Global Positioning System (GPS) Speed Measurement via GPS Simulation	Internal	May – August 2015
7	Evaluation of the Effect of Global Positioning System (GPS) Antenna Orientation on GPS Performance	Internal	October 2015 – August 2016
8	Evaluation of Global Positioning System (GPS) Adjacent Band Compatibility via GPS Simulation	Internal	October 2016 – Current
9	Simulation and Modelling of Global Navigation Satellite System (GNSS) Vulnerabilities	Proposed for RMK11	January 2018 – December 2019



Presentation Outline

- ◆ Review of activities conducted on vulnerabilities of GPS to:
 - ◆ Radio frequency interference (RFI)
 - ◆ Simplistic spoofing
 - ◆ Static multipath
 - ◆ GPS satellite clock error
 - ◆ Power consumption
 - ◆ Speed measurement
 - ◆ Antenna orientation

- ◆ Future research direction:
 - ◆ Intermediate spoofing
 - ◆ Dynamic multipath
 - ◆ Ionospheric and tropospheric delays
 - ◆ Extension to other GNSS systems; GLONASS, BeiDou and Galileo





GNSS Antenna Orientation

- ◆ Antennas are a critical part of any GNSS receiver design and their importance cannot be stated highly enough.
- ◆ GNSS signals are extremely weak and present unique demands on the antenna.
- ◆ Even the best receiver cannot bring back what has been lost due to a poor antenna design.
- ◆ The choice and implementation of the antenna plays a significant role in GNSS performance





GNSS Antenna Orientation

- ◆ Ideally, a GNSS antenna should have an isotropic response pattern that is independent of its orientation or direction of arrival of GNSS signals.
- ◆ However, there are no ideal antennas in the real world and real antennas do not have an isotropic response pattern.
- ◆ This means that the same signal received at various antenna orientations can result in stronger or weaker signals being presented to the receiver front end.
- ◆ To this end, the evaluation of the effect of GNSS antenna orientation on GNSS performance has received significant attention





Objective

- ◆ This study is aimed at evaluating the effect of GPS antenna orientation for three Garmin GPS receivers that use built-in quad helix antennas;
 - ◆ GPSmap 60CSx
 - ◆ GPSmap 62Cs
 - ◆ Oregon 550

Methodology

The following assumptions are made for the tests conducted:

- No ionospheric or tropospheric delays
- No clock and ephemeris error
- No unintended multipath fading or obstructions
- No interference signals

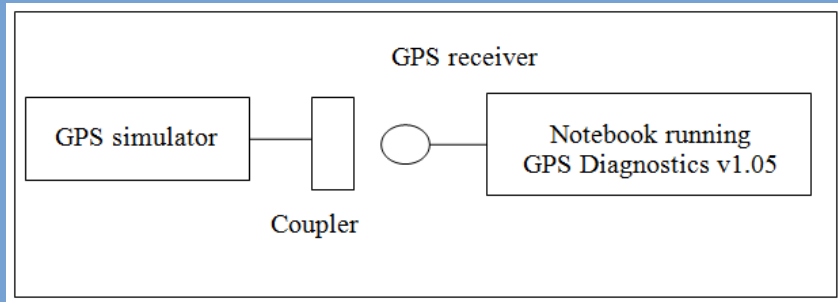
Test locations:

- N 2° 58' E 101° 48' (Kajang, Selangor, Malaysia)
- N 39° 45' W 105° 00' (Denver, Colorado, USA)
- S 16° 55' E 145° 46' (Cairns, Queensland, Australia)
- S 51° 37' W 69° 12' (Rio Gallegos, Argentina)

UTC times:

- 0000
- 0300
- 0600
- 0900

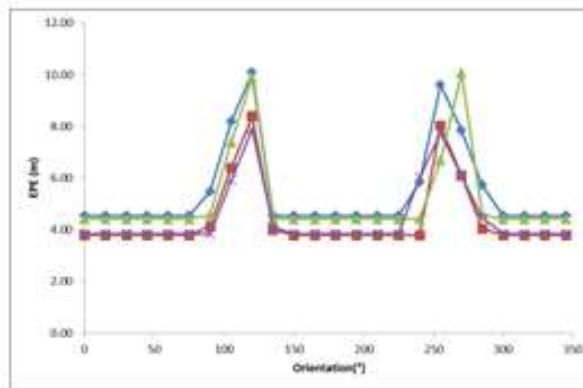
Readings are taken for GPS antenna orientations of 0 to 345°, at increments of 15°. For each reading, values of estimate probable error (EPE) are recorded for a period of 15 min.



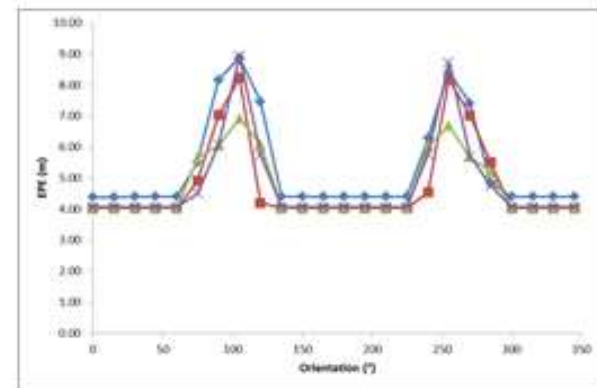


Results & Discussion

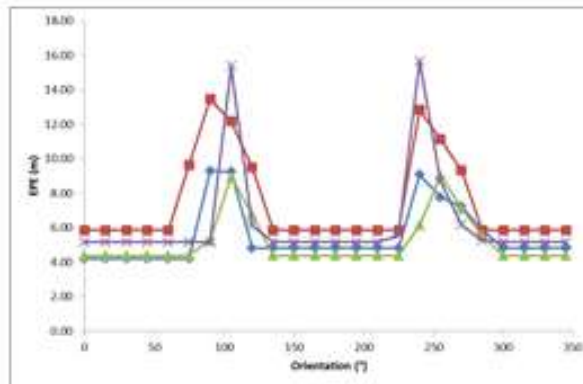
GPSmap 60CSx



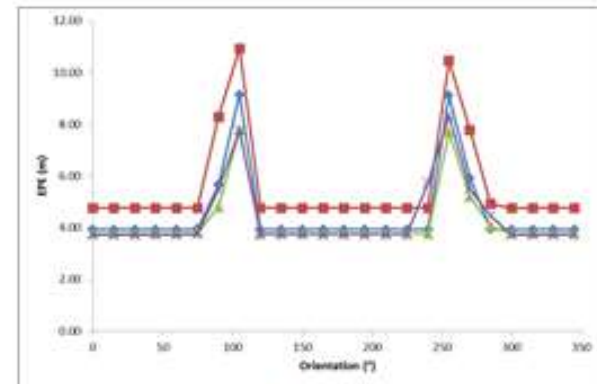
(a)



(b)



(c)



(d)

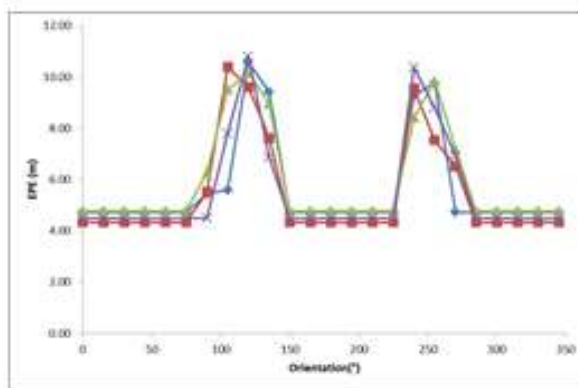
—♦— UTC 0000 —■— UTC 0600 —▲— UTC 1200 —×— UTC 1800

Recorded EPE values for the GPSmap 60CSx receiver: (a) Kajang (b) Denver (c) Cairns (d) Rio Gallegos.

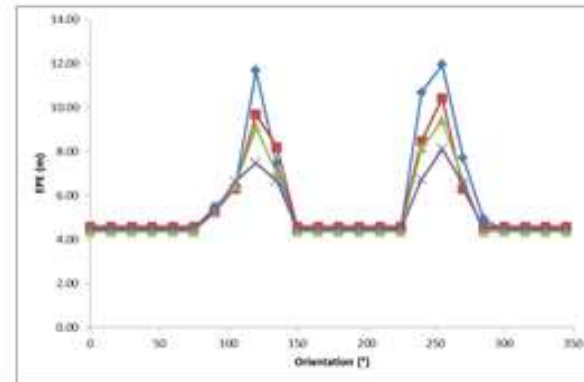


Results & Discussion

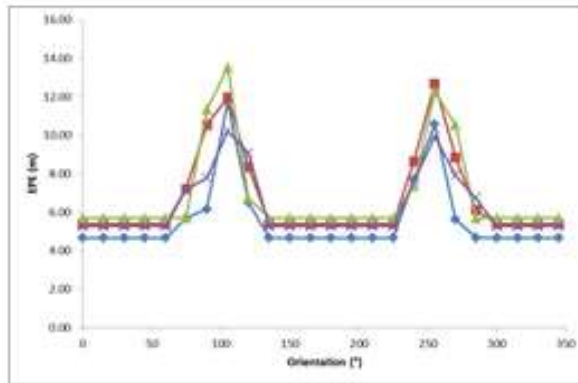
GPSmap 62Cs



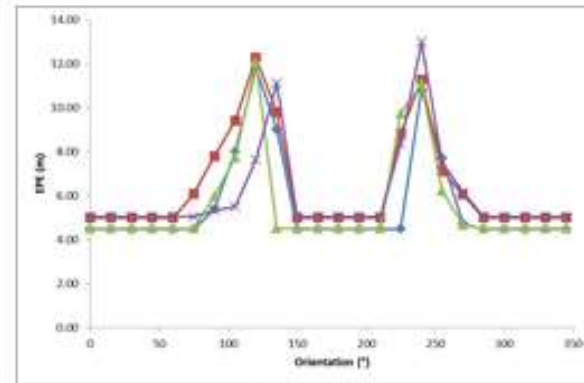
(a)



(b)



(c)



(d)

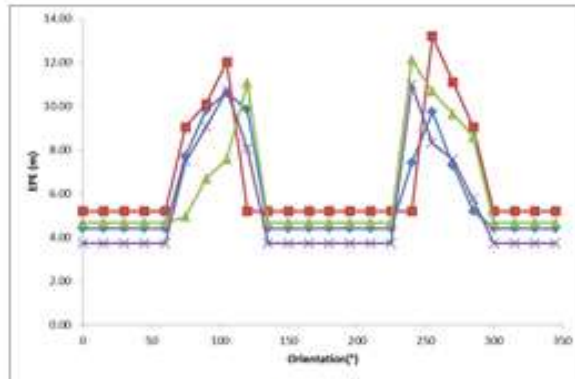
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Recorded EPE values for the GPSmap 62Cs receiver: (a) Kajang (b) Denver (c) Cairns (d) Rio Gallegos.

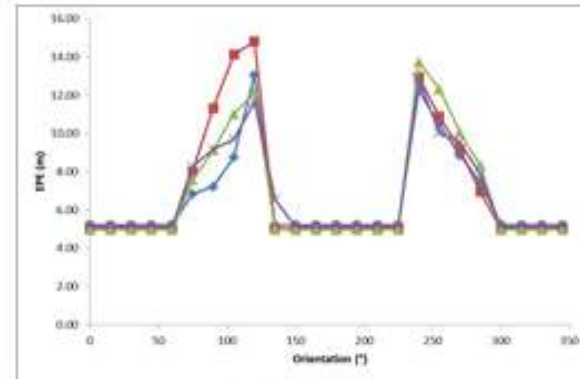


Results & Discussion

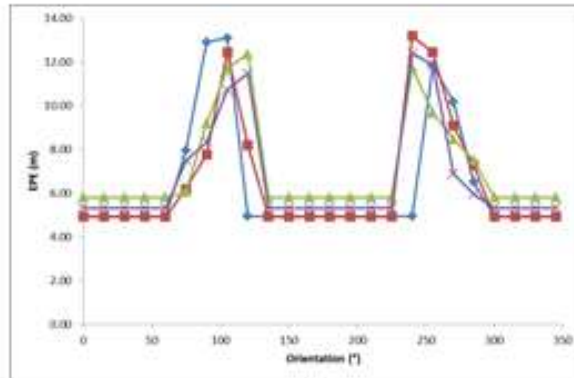
Oregon 550



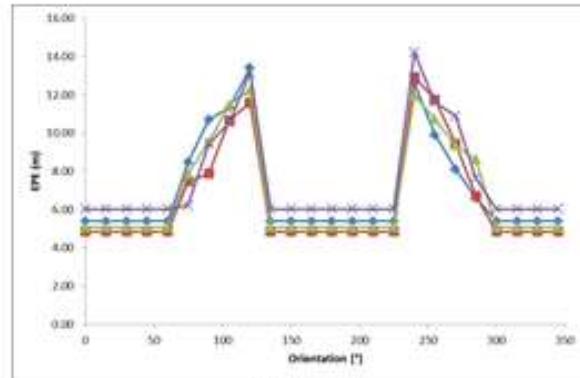
(a)



(b)



(c)



(d)

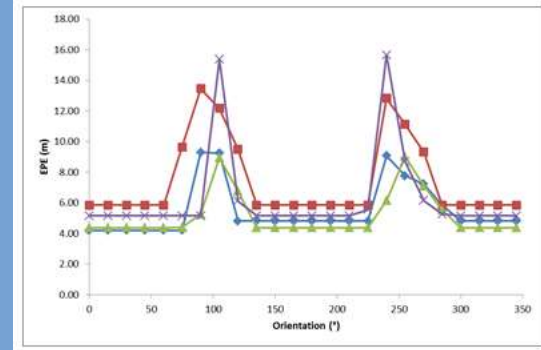
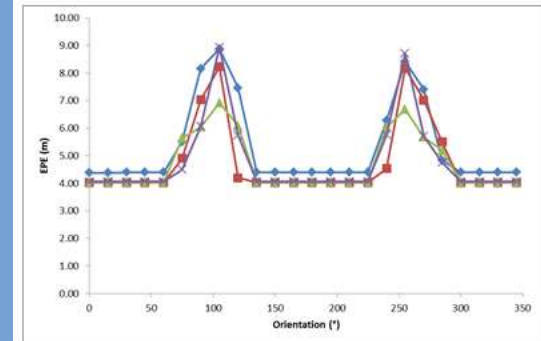
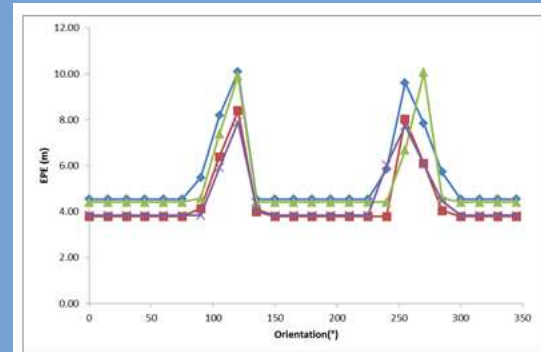
—◆— UTC 0000 —■— UTC 0600 —▲— UTC 1200 —×— UTC 1800

Recorded EPE values for the Oregon 550 receiver: (a) Kajang (b) Denver (c) Cairns (d) Rio Gallegos.



Results & Discussion

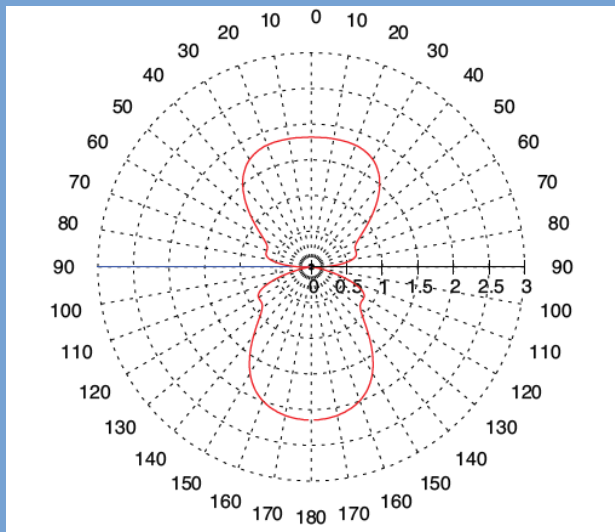
- ◆ It is found that there is degradation of accuracy for antenna orientations of 75 to 120° and 240 to 285°.
- ◆ This indicates that for these orientations, the antenna gain is lower, resulting in reduced carrier-to-noise density (C/N_0) levels for GPS satellites tracked by the receivers, which is the ratio of received GPS signal power level to noise density.
- ◆ Lower C/N_0 levels result in increased data bit error rate when extracting navigation data from GPS signals, and hence, increased carrier and code tracking loop jitter.
- ◆ This, in turn, results in more noisy range measurements and thus, less precise positioning.
- ◆ For the remaining orientations, the performance remains constant.





Results & Discussion

- ◆ These results indicate that the quad helix antennas are operating in endfire and backfire modes simultaneously.
- ◆ While this type of design has smaller antenna gain than quad helix antennas that use only endfire or backfire modes, it allows for a more isotropic antenna performance.



Example of the radiation pattern of a quad helix antenna operating in endfire and backfire modes simultaneously



Conclusion

- ◆ It was found that there was degradation of accuracy for orientations of 75 to 120° and 240 to 285°.
- ◆ For the remaining orientations, the accuracy remained constant. This indicates that the quad helix antennas are operating in endfire and backfire modes simultaneously.
- ◆ While this type of design has smaller antenna gain than quad helix antennas that use only endfire or backfire modes, it allows for a more isotropic antenna performance.
- ◆ This study will be extended to evaluate the performance of antennas of a wider range of GPS receivers.



Scope for Future Work

- ◆ The proposed scope for future work includes the extension of this study to perform the simulation and modelling of:
 - ◆ Intermediate spoofing
 - ◆ Dynamic multipath
 - ◆ Ionospheric and tropospheric delays
 - ◆ Extension to other GNSS systems; GLONASS, BeiDou and Galileo



GPS Functional Tests



Pendulum Instruments
GPS-12R



Magellan Z-Max



Trimble Geoexplorer
6000 GeoXH, Nomad
900G and Juno SB



Topcon Hiper GA



Trimble R8



ProMark 200

Research Collaborations

◆ Effect of Radio Frequency Interference (RFI) on Global Positioning System (GPS) Static Observations (2012)

- ◆ Collaboration with the Faculty of Architecture, Planning and Surveying (FSPU), Universiti Teknologi MARA (UiTM)
- ◆ Project Co-Leaders:
 - ◆ Assoc. Prof. Sr. Dr. Azman Mohd Suldi
 - ◆ Mr. Ahmad Norhisyam Idris



◆ Power Efficient Global Positioning System (GPS) Receiver Design (2014)

- ◆ Collaboration with the Department of Computer and Communication Systems Engineering, Universiti Putra Malaysia (UPM)
- ◆ Project Co-Leaders:
 - ◆ Dr. Fakhrol Zaman Rokhani
 - ◆ Mr. Fawaz Mohamed Jumaah





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